

wherein each of the first and second flight termination devices has an ability to independently terminate a flight of the unmanned balloon based on a determination of a malfunction of the unmanned balloon; and transmitting data from the airborne platform.

15. The method of claim **14**, the system further comprising an antenna and at least two geographical coordinates tracking system wherein the sensor comprises a pressure sensor;

wherein the at least two separate power sources are for powering the first and second flight termination devices; wherein, in operation, the unmanned balloon substantially drifts along with the wind currents; wherein the payload remains attached to the unmanned balloon as one when landed unless the payload is separated from the unmanned balloon; wherein the transceiver is capable of communicating with a communication device that is separate from the unmanned balloon.

16. The method of claim **14**, wherein the airborne platform is configured to reduce or eliminate a chance of the airborne platform becoming a free floating, uncontrolled transmitter.

17. The method of claim **16**, wherein the airborne platform is configured to reduce or eliminate a chance of the airborne platform becoming a free floating, uncontrolled transmitter by monitoring sensed information of the airborne platform and by comparing the sensed information to known geographic or altitude based boundaries.

18. The method of claim **17**, wherein the sensed information comprises coordinates and velocities.

19. The method of claim **14**, wherein the tether comprises a line.

20. The method of claim **14**, wherein the payload is configured to communicate with an additional airborne payload attached to a separate unmanned balloon.

21. The system of claim **1**, wherein the unmanned balloon substantially drifts along with the wind currents taking into account the wind currents.

22. The system of claim **4**, wherein the unmanned balloon substantially drifts along with the wind currents taking into account the wind currents.

23. The system of claim **1**, wherein the unmanned balloon substantially drifts along with the wind currents taking into account the wind currents to prevent the airborne platform from becoming an uncontrolled lighter-than-air airborne platform.

24. The system of claim **4**, wherein the unmanned balloon substantially drifts along with the wind currents taking into account the wind currents to prevent the airborne platform from becoming an uncontrolled lighter-than-air airborne platform.

25. The method of claim **11**, wherein the unmanned balloon substantially drifts along with the wind currents taking into account the wind currents.

26. The method of claim **14**, wherein the unmanned balloon substantially drifts along with the wind currents taking into account the wind currents.

27. The method of claim **11**, wherein the unmanned balloon substantially drifts along with the wind currents taking into account the wind currents to prevent the airborne platform from becoming an uncontrolled lighter-than-air airborne platform.

28. The method of claim **14**, wherein the unmanned balloon substantially drifts along with the wind currents taking into account the wind currents to prevent the airborne platform from becoming an uncontrolled lighter-than-air airborne platform.

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